

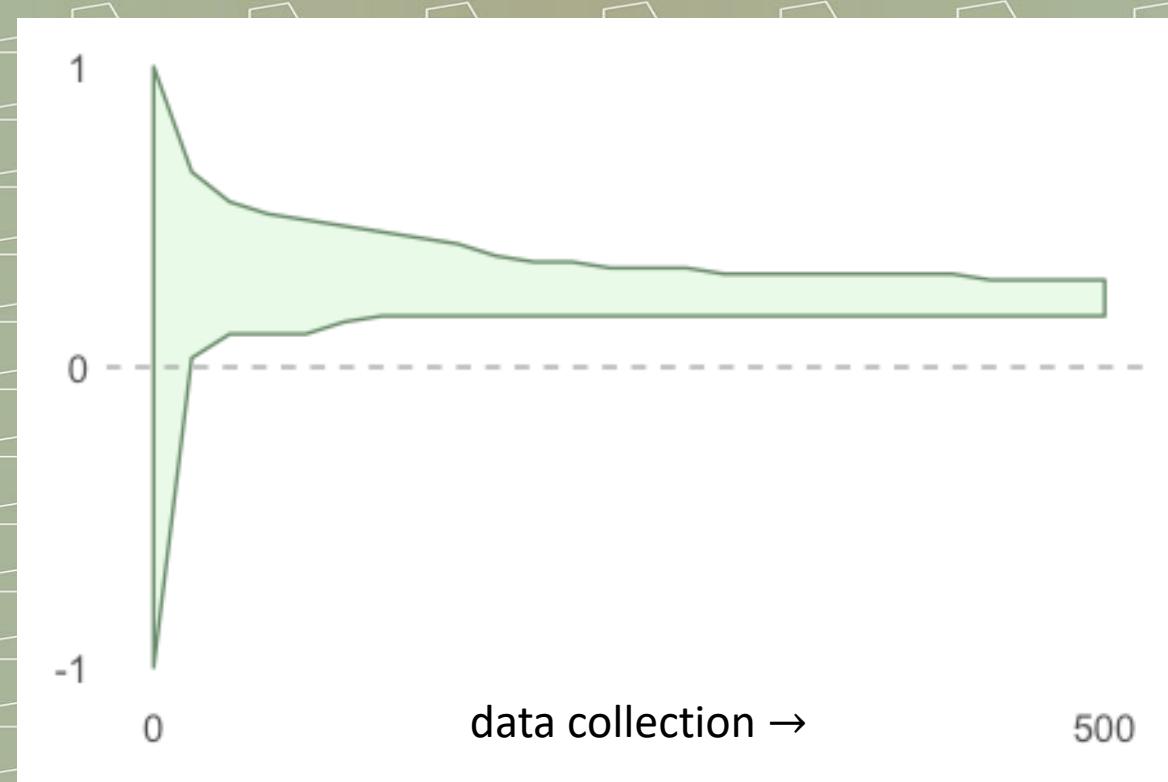
Anytime-valid Confidence Intervals for Contingency Tables and Beyond

Rosanne J. Turner

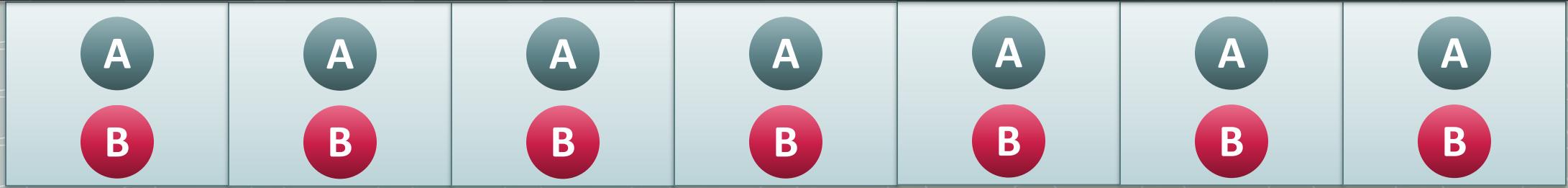
SAVI Workshop 2022

Joint work with Peter Grünwald

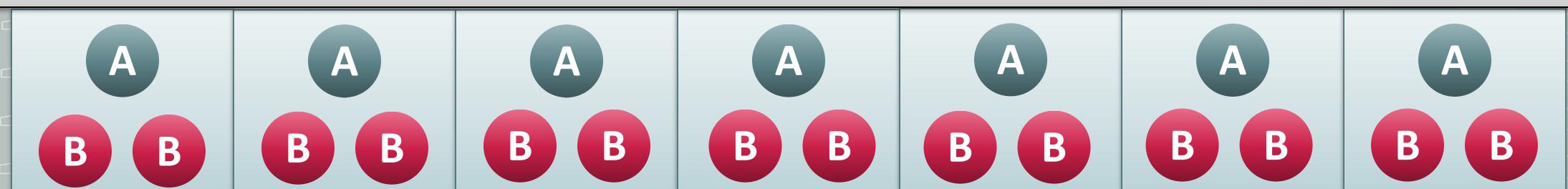
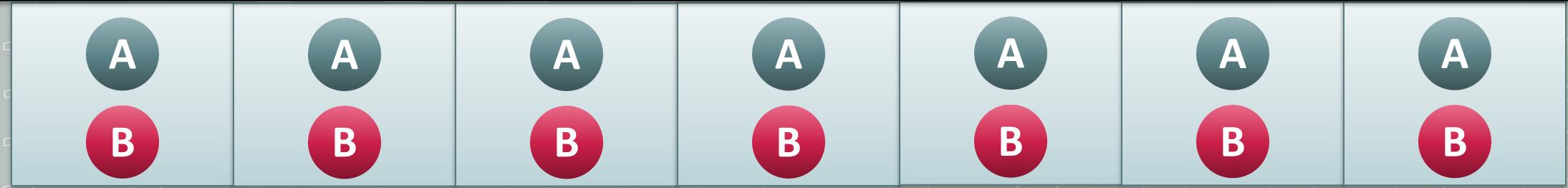
**Goal: tests that can
be used under
optional stopping,
with a notion of
effect size**



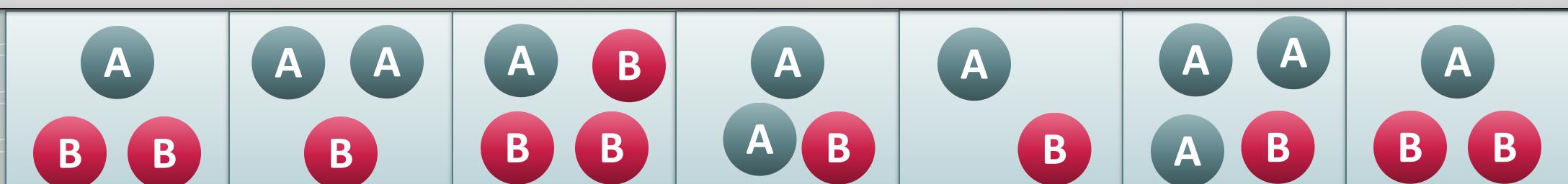
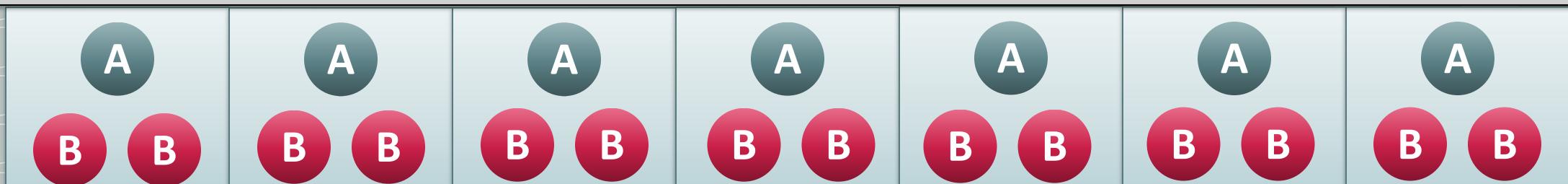
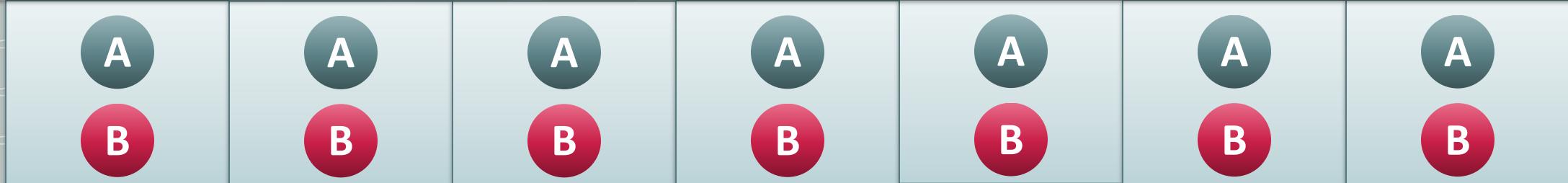
Setup



Setup



Setup



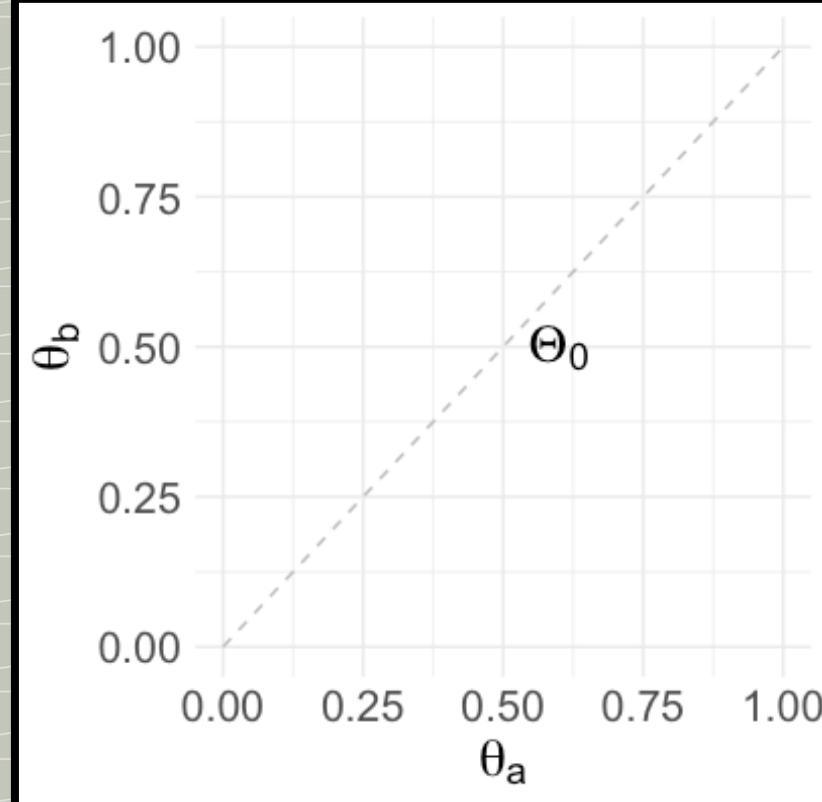
Setup

- $\mathcal{M} = \{P_\theta : \theta \in \Theta\}$ general parametric model, set of prob. distrs with densities or mass functions p_θ for random variable Y
- Two i.i.d. data streams $Y_{1,a}, Y_{2,a}, \dots$ and $Y_{1,b}, Y_{2,b}, \dots$
- Want to create E-variable for block of n_a outcomes in group a , n_b outcomes in group b :
$$Y_a^{n_a} = (Y_{1,a}, \dots, Y_{n_a,a}), Y_b^{n_b} = (Y_{1,b}, \dots, Y_{n_b,b})$$
- Take simple \mathcal{H}_1 indexed by (θ_a, θ_b) :
likelihood is $\prod_{i=1..n_a} p_{\theta_a}(Y_{i,a}) \cdot \prod_{i=1..n_b} p_{\theta_b}(Y_{i,b})$
- Classical \mathcal{H}_0 in this setting: $\theta_a = \theta_b$, i.e. the set of distributions indexed by $\{(\theta_0, \theta_0) : \theta_0 \in \Theta\}$

Running example: 2x2 contingency table setting

Do success probabilities differ between 2 strategies?

- \mathcal{H}_0 : observations $Y \in \{0,1\}$ independent of strategy $X \in \{a, b\}$
- Equivalently, when $Y_x \stackrel{i.i.d.}{\sim} \text{Bernoulli}(\theta_x)$:
 $\mathcal{H}_0: \theta_a = \theta_b$.



Idea through numerical optimization for finding GROW E-variable

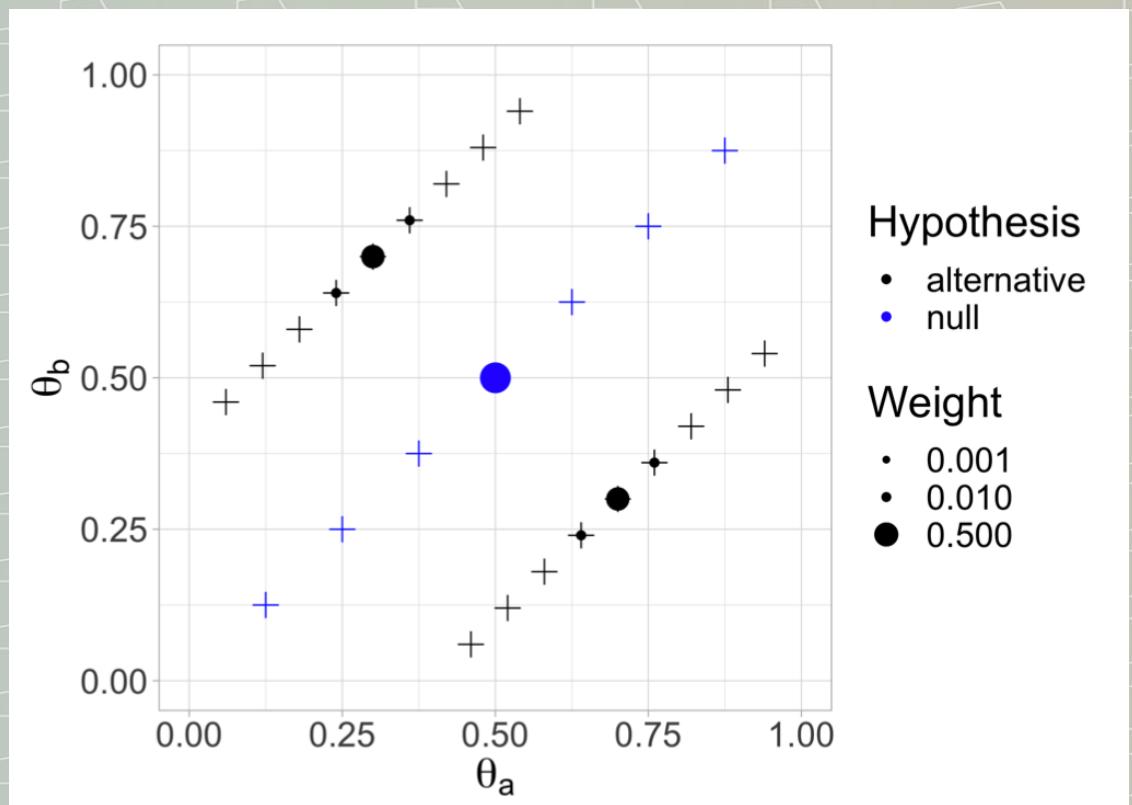


Figure 2.1a from Turner (2019), master thesis at Leiden University

Main Theorem of Turner et al. (2021)

Under no further regularity conditions, with $n = n_a + n_b$,

$$S^* := \prod_{i=1..n_a} \frac{p_{\theta_a}(Y_{i,a})}{\frac{n_a}{n} p_{\theta_a}(Y_{i,a}) + \frac{n_b}{n} p_{\theta_b}(Y_{i,a})} \cdot \prod_{i=1..n_b} \frac{p_{\theta_b}(Y_{i,b})}{\frac{n_a}{n} p_{\theta_a}(Y_{i,b}) + \frac{n_b}{n} p_{\theta_b}(Y_{i,b})}$$

is an e-variable for the classical \mathcal{H}_0

If $\mathcal{M} = \{p_\theta : \theta \in \Theta\}$ is convex, S^* is the **(θ_a, θ_b) -GRO e-variable**, achieving
 $\max_S \mathbf{E}_{Y_a^{n_a} \sim P_{\theta_a}, Y_b^{n_b} \sim P_{\theta_b}} [\log S]$ where the maximum is over all e-variables
relative to \mathcal{H}_0

Proof sketch (i)

Let $G \in \{a, b\}$ satisfy $P(G = a) = \frac{n_a}{n}$ under both H_0 and H_1

- Apart from G **there is now just 1 (not $n!$) RV, Y**
- We observe (G, Y) .
 - Under \mathcal{H}_1 , (still a simple hypothesis indexed by (θ_a, θ_b)), $Y \sim P_{\theta_G}$
 - Under \mathcal{H}_0 (still a composite hypothesis with parameter $\theta_0 \in \Theta$), $Y \sim P_{\theta_0}$ independently of G
- We will design an e-variable for this **modified testing problem** in which we randomize between observing an outcome from group a and b and then link it to our original problem in which we observe n_a and n_b of each (this proof technique may have broader applications...)

Proof sketch (ii)

Let $G \in \{a, b\}$ satisfy $P(G = a) = \frac{n_a}{n}$ under both H_0 and H_1

- We observe (G, Y) .
 - Under \mathcal{H}_1 , (still a simple hypothesis indexed by (θ_a, θ_b)), $Y \sim P_{\theta_G}$
 - Under \mathcal{H}_0 (still a composite hypothesis with parameter $\theta_0 \in \Theta$) , $Y \sim P_{\theta_0}$ independently of G
- $s(G, Y) := \frac{p_{\theta_G}(Y)}{\frac{n_a}{n}p_{\theta_a}(Y) + \frac{n_b}{n}p_{\theta_b}(Y)}$ is an e-variable, since under all distributions in the null, i.e. for all $\theta_0 \in \Theta$,
$$\mathbf{E}_G \mathbf{E}_{Y \sim P_{\theta_0}} [s(G, Y)] = \frac{n_a}{n} \mathbf{E}_{Y \sim P_{\theta_0}} [s(a, Y)] + \frac{n_b}{n} \mathbf{E}_{Y \sim P_{\theta_0}} [s(b, Y)] = 1$$

Proof sketch (iii)

We thus have $\frac{n_a}{n} \mathbf{E}_{Y \sim P_{\theta_0}}[s(a, Y)] + \frac{n_b}{n} \mathbf{E}_{Y \sim P_{\theta_0}}[s(b, Y)] = 1$.

Young's inequality now gives $(\mathbf{E}_{Y \sim P_{\theta_0}}[s(a, Y)])^{n_a} \cdot (\mathbf{E}_{Y \sim P_{\theta_0}}[s(b, Y)])^{n_b} \leq 1$ (*)

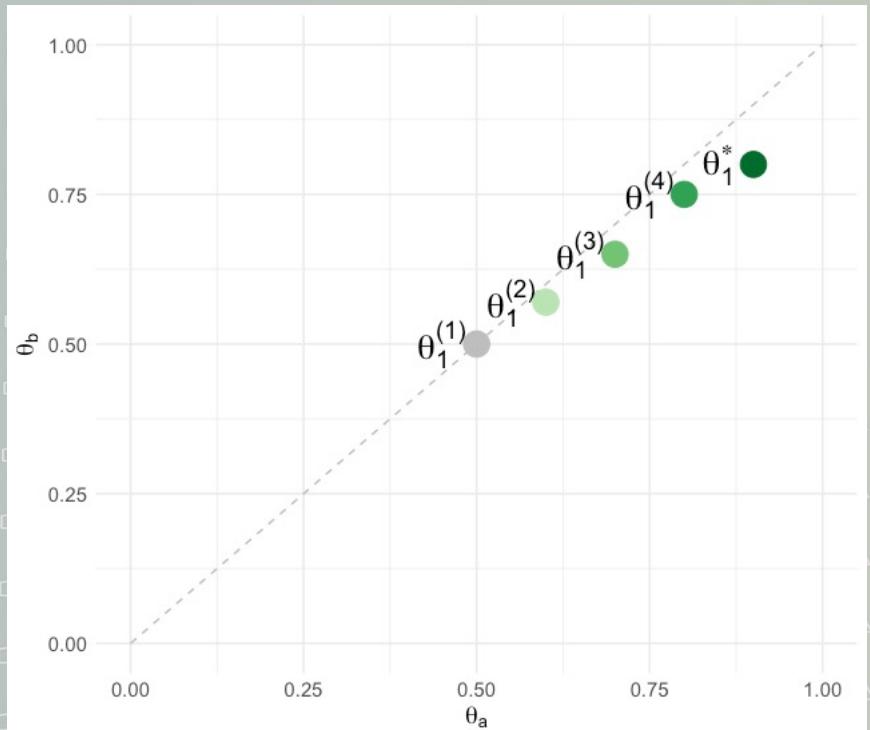
In original problem, we observe $n_a Y_a$'s and $n_b Y_b$'s. We need to show

$$S^* := \prod_{i=1}^{n_a} \frac{p_{\theta_a}(Y_{i,a})}{\frac{n_a}{n} p_{\theta_a}(Y_{i,a}) + \frac{n_b}{n} p_{\theta_b}(Y_{i,a})} \cdot \prod_{i=1}^{n_b} \frac{p_{\theta_b}(Y_{i,b})}{\frac{n_a}{n} p_{\theta_a}(Y_{i,b}) + \frac{n_b}{n} p_{\theta_b}(Y_{i,b})}$$

is an e-variable. Using first independence and then (*) we get

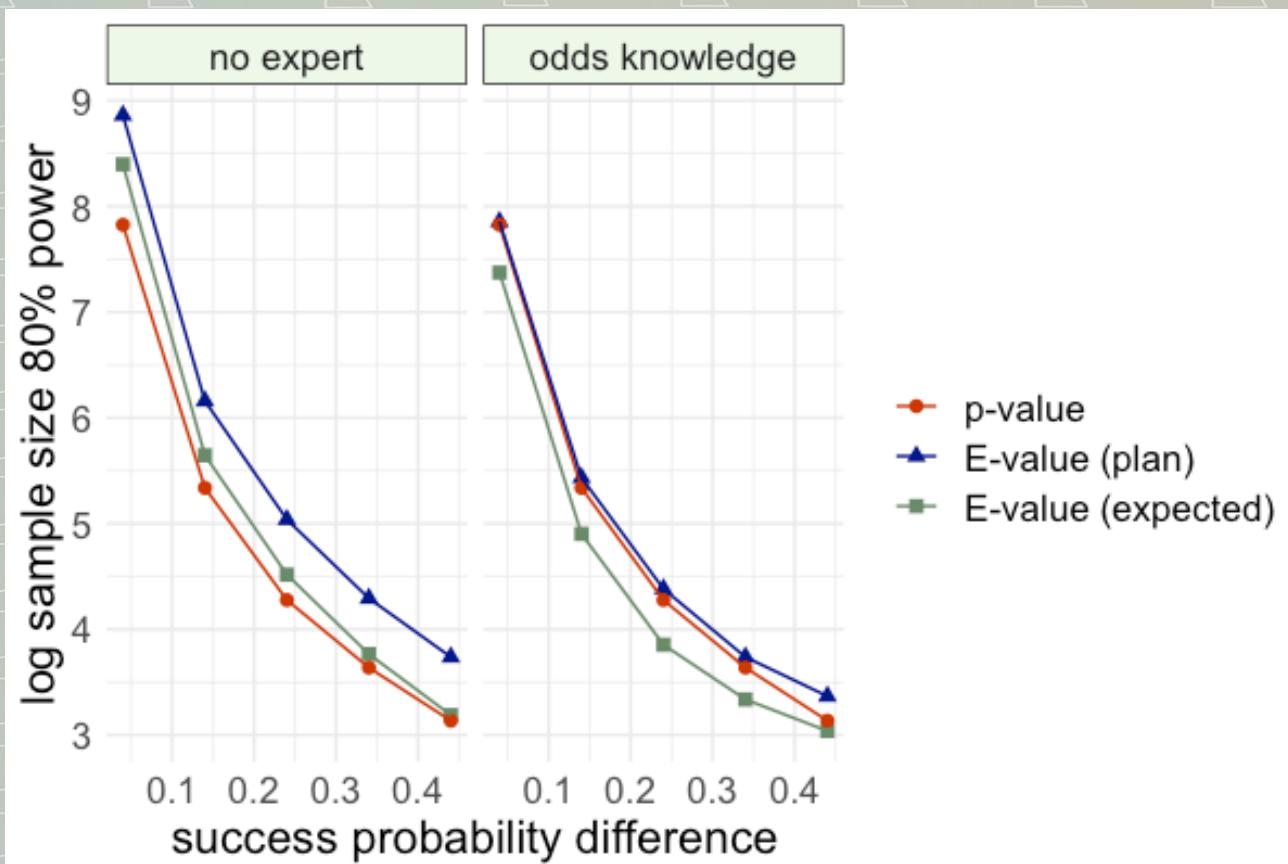
$$\mathbf{E}_{Y^n \sim P_{\theta_0}}[S^*] = \left(\mathbf{E}_{Y \sim P_{\theta_0}} \left(\frac{p_{\theta_a}(Y)}{\frac{n_a}{n} p_{\theta_a}(Y) + \frac{n_b}{n} p_{\theta_b}(Y)} \right) \right)^{n_a} \cdot \left(\mathbf{E}_{Y \sim P_{\theta_0}} \left(\frac{p_{\theta_b}(Y)}{\frac{n_a}{n} p_{\theta_a}(Y) + \frac{n_b}{n} p_{\theta_b}(Y)} \right) \right)^{n_b} \leq 1$$

Estimate (θ_a, θ_b) based on past blocks



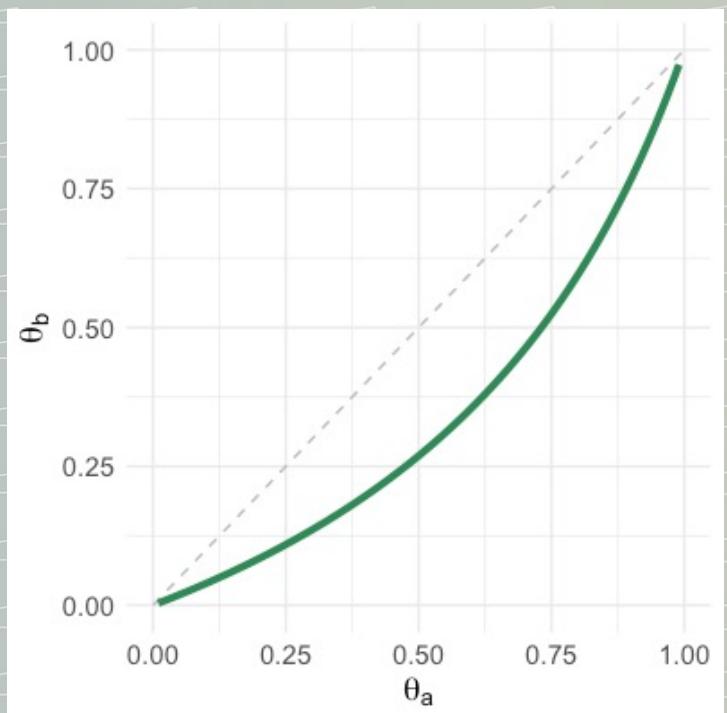
- Allowed to estimate (θ_a, θ_b) for each new data block, based on past data
 - Maximum likelihood
 - MAP estimator
 - Posterior mean, ...
- Restrict search space based on expert knowledge

Simulated example: 2x2 E-values vs classical counterpart

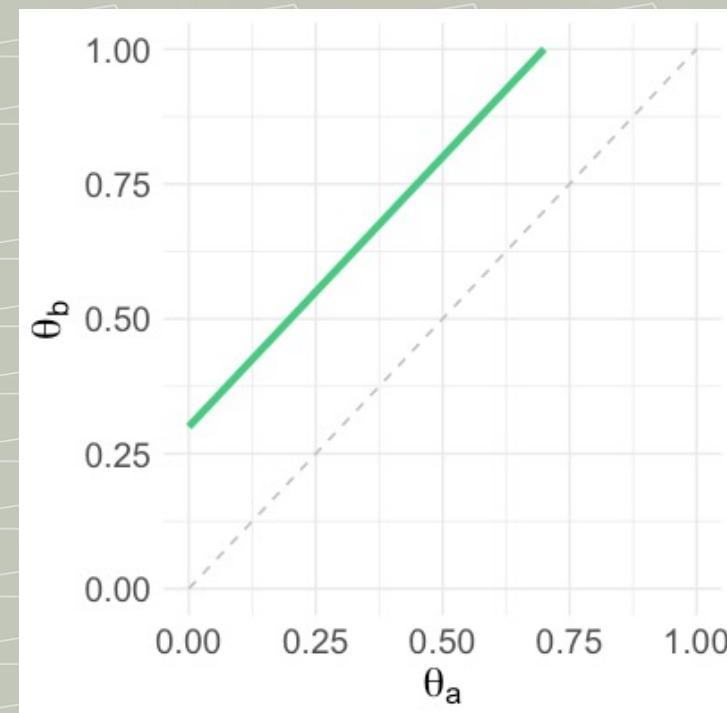


Extension to general \mathcal{H}_0

$$\Theta_0(\delta) = \{(\theta_a, \theta_b) : lOR(\theta_b, \theta_a) = -1\}$$



$$\Theta_0(\delta) = \{(\theta_a, \theta_b) : \theta_b - \theta_a = 0.3\}$$



E-variable for two-stream data, general \mathcal{H}_0

Theorem (Turner and Grünwald, 2022):

$$S_{\Theta_0}(Y^{(1)}) := \prod_{i=1}^{n_a} \frac{p_{\widehat{\theta}_a}(Y_{i,a})}{p_{\theta_a^\circ}(Y_{i,a})} \prod_{i=1}^{n_b} \frac{p_{\widehat{\theta}_b}(Y_{i,b})}{p_{\theta_b^\circ}(Y_{i,b})}, \text{ where } (\theta_a^\circ, \theta_b^\circ) \text{ achieve}$$
$$\min_{(\theta_a, \theta_b) \in \Theta_0(\delta)} D(P_{\widehat{\theta}_a, \widehat{\theta}_b}(Y_a^{n_a}, Y_b^{n_b}) | P_{\theta_a, \theta_b}(Y_a^{n_a}, Y_b^{n_b})),$$

is an E-variable for $\mathcal{H}_0 := \{P_{\theta_a, \theta_b} : (\theta_a, \theta_b) \in \Theta_0(\delta)\}$

- We will neither precisely state nor prove the general result, but give an idea of the general way that allows us to establish E-variables for general \mathcal{H}_0 / Θ_0 with $\theta_a \neq \theta_b$
- Once again, we do this for the modified problem in which we observe a single random variable rather than $n_a + n_b$ of them

General \mathcal{H}_0 : proof idea

Let $G \in \{a, b\}$ satisfy $p(a) := P(G = a) = \frac{n_a}{n}$ under both H_0 and H_1

- Apart from G there is now just 1 RV, Y
- We observe (G, Y) .
 - Under \mathcal{H}_1 , (simple hypothesis indexed by (θ_a, θ_b)),
 $p_{\theta_a, \theta_b}(G, Y) := p(G)p_{\theta_a, \theta_b}(Y | G)$ with $p_{\theta_a, \theta_b}(Y | G = g) := p_{\theta_g}(Y)$
 - Similarly under \mathcal{H}_0 (composite hypothesis with free param. $(\theta_a^*, \theta_b^*) \in \Theta_0^* \subset \Theta^2$),
 $p_{\theta_a^*, \theta_b^*}(G, Y) := p(G)p_{\theta_a^*, \theta_b^*}(Y | G)$
with $p_{\theta_a^*, \theta_b^*}(Y | G = g) := p_{\theta_g^*}(Y)$
 - Let W be prior on Θ_0^* . Let $p_W(G, Y) := \int p_{\theta_a^*, \theta_b^*}(G, Y) dW(\theta_a^*, \theta_b^*)$

Then $s(G, Y) := \frac{p_{\theta_g}(Y)}{p_{W_0^*}(Y)}$ is an e-variable,

where W_0^* is the RIPr of (G., De Heide, Koolen, 2019, Thm 1) of P_{θ_a, θ_b} onto Θ_0^*

General \mathcal{H}_0 : proof idea

Theorem (Turner and Grünwald, 2022):

$$S_{\Theta_0}(Y^{(1)}) := \prod_{i=1}^{n_a} \frac{p_{\widehat{\theta}_a}(Y_{i,a})}{p_{\theta_a^\circ}(Y_{i,a})} \prod_{i=1}^{n_b} \frac{p_{\widehat{\theta}_b}(Y_{i,b})}{p_{\theta_b^\circ}(Y_{i,b})}, \text{ where } (\theta_a^\circ, \theta_b^\circ) \text{ achieve}$$
$$\min_{(\theta_a, \theta_b) \in \Theta_0(\delta)} D(P_{\widehat{\theta}_a, \widehat{\theta}_b}(Y_a^{n_a}, Y_b^{n_b}) | P_{\theta_a, \theta_b}(Y_a^{n_a}, Y_b^{n_b})),$$

is an E-variable for $\mathcal{H}_0 := \{P_{\theta_a, \theta_b} : (\theta_a, \theta_b) \in \Theta_0(\delta)\}$

- It turns out that $s(G, Y) := \frac{p_{\theta_g}(Y)}{p_{W_0^*}(Y)}$ reduces to the previous construction for the classical \mathcal{H}_0
- It can once again be linked to an E-variable in the original problem
- In the Bernoulli case, with convex Θ_0 , we then get the stated result.

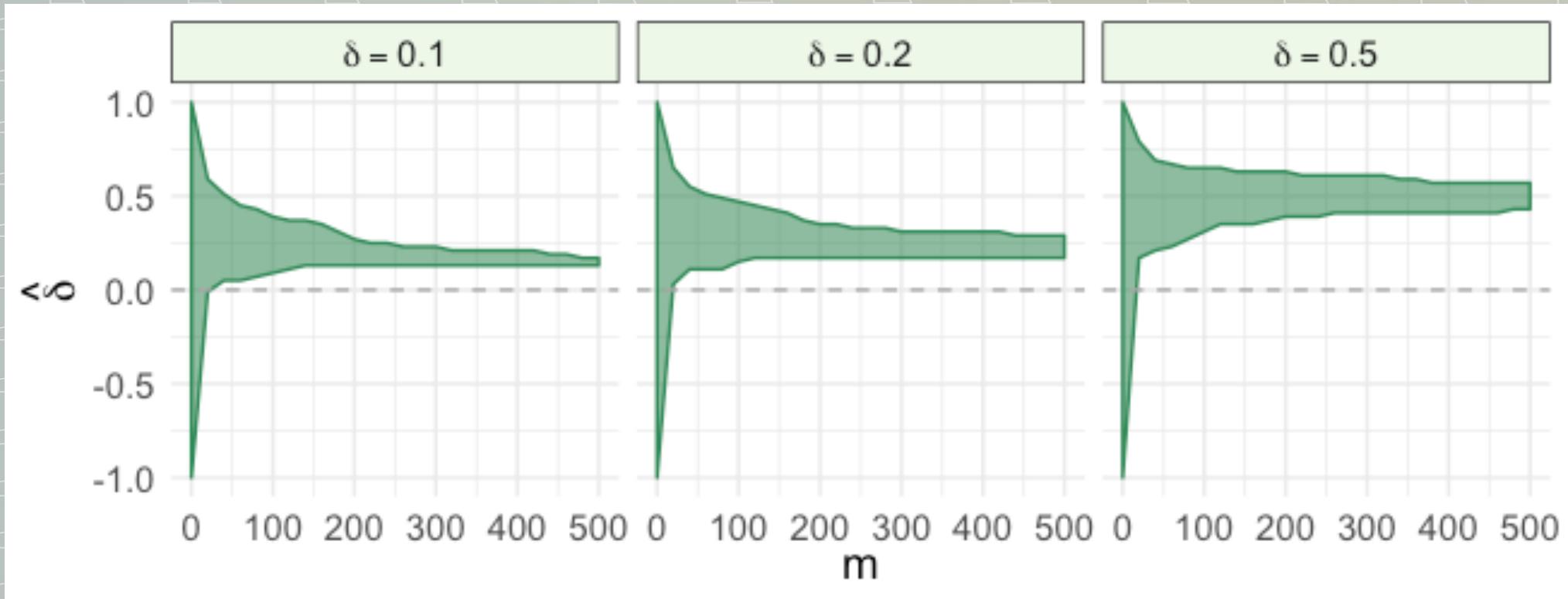
Anytime-valid confidence sequences

Goal: confidence sequence CS with coverage at level $(1 - \alpha)$:

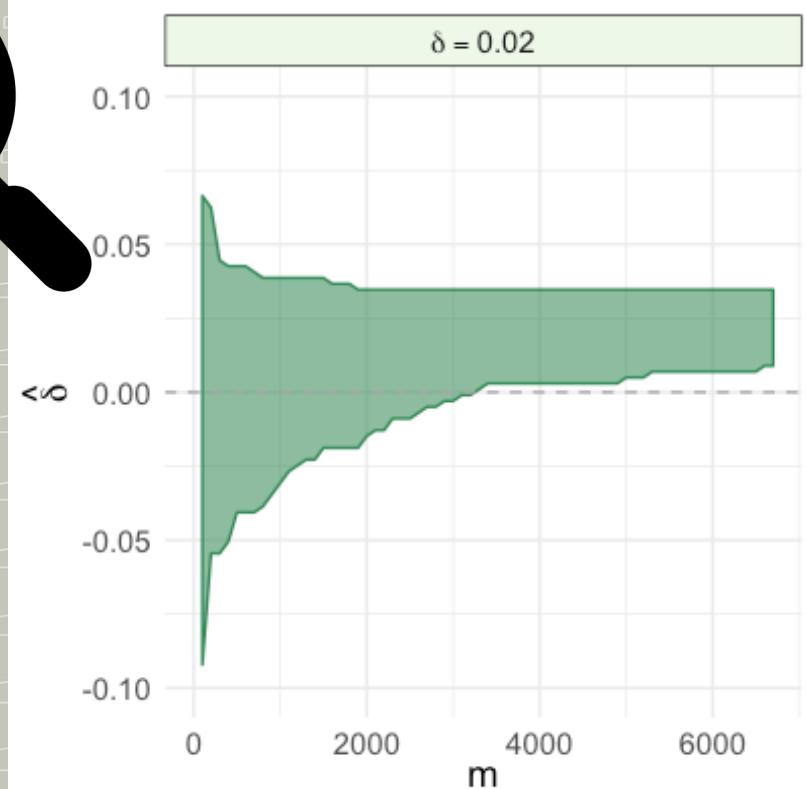
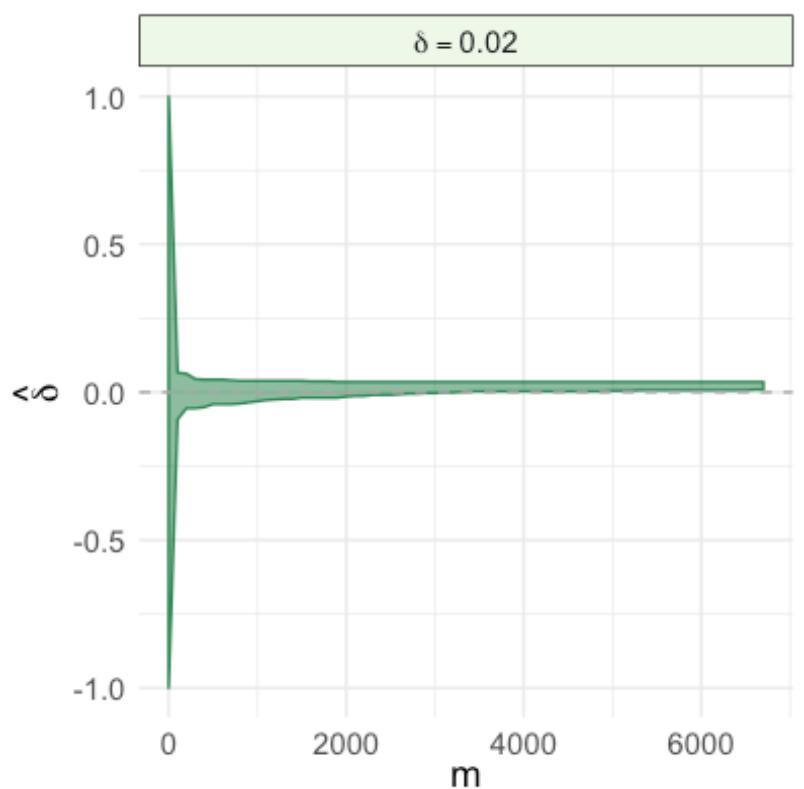
- $P_{\theta_a, \theta_b}(\text{ for any } m = 1, 2, \dots : \delta(\theta_a, \theta_b) \notin CS_{(m)}) \leq \alpha$
- $\delta(\theta_a, \theta_b)$: arbitrary notion of effect size

- Construct $CS_{\alpha, (m)} = \left\{ \delta : S_{\Theta_0(\delta)}^{(m)} \leq \frac{1}{\alpha} \right\}$
- Gives desired coverage because $S_{\Theta_0(\delta)}^{(m)}$ is an E-variable and offers Type-I error guarantee at level α

Simulations: risk difference

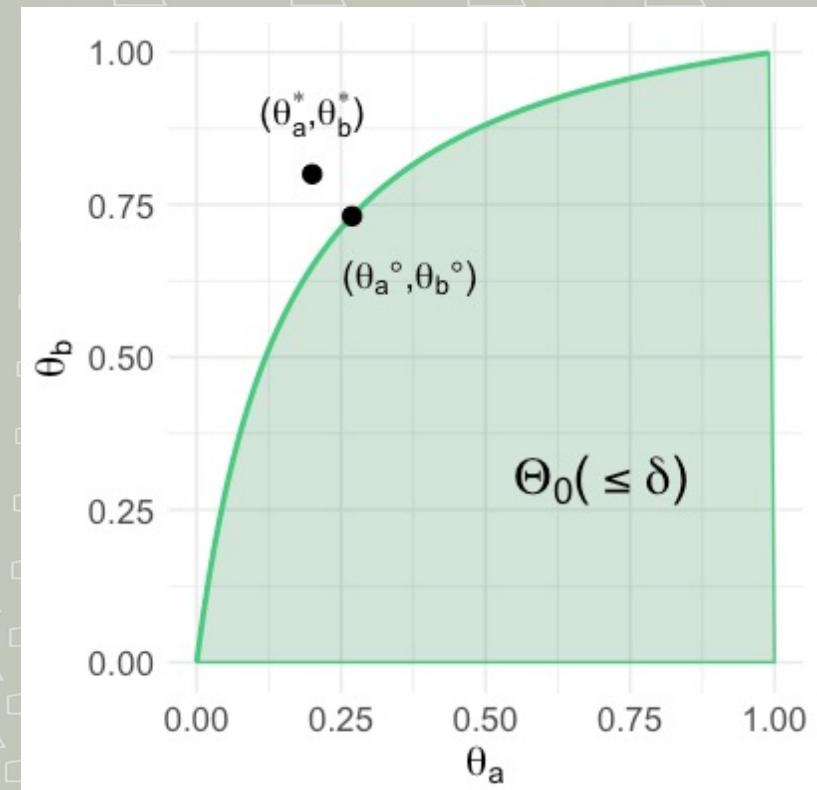


Simulations: risk difference



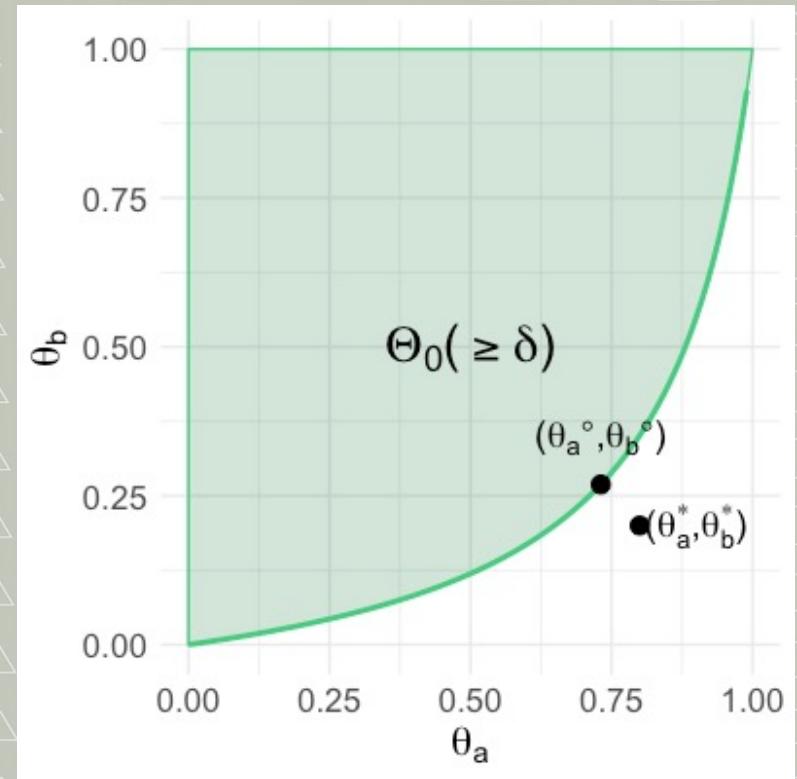
Tricky case: odds ratio and convexity of \mathcal{H}_0

- Need convexity of $\Theta_0(\delta)$ to construct E-variable
- $\delta > 0 \rightarrow$ can estimate lower bound (see figure)
- $\delta < 0 \rightarrow$ can estimate upper bound

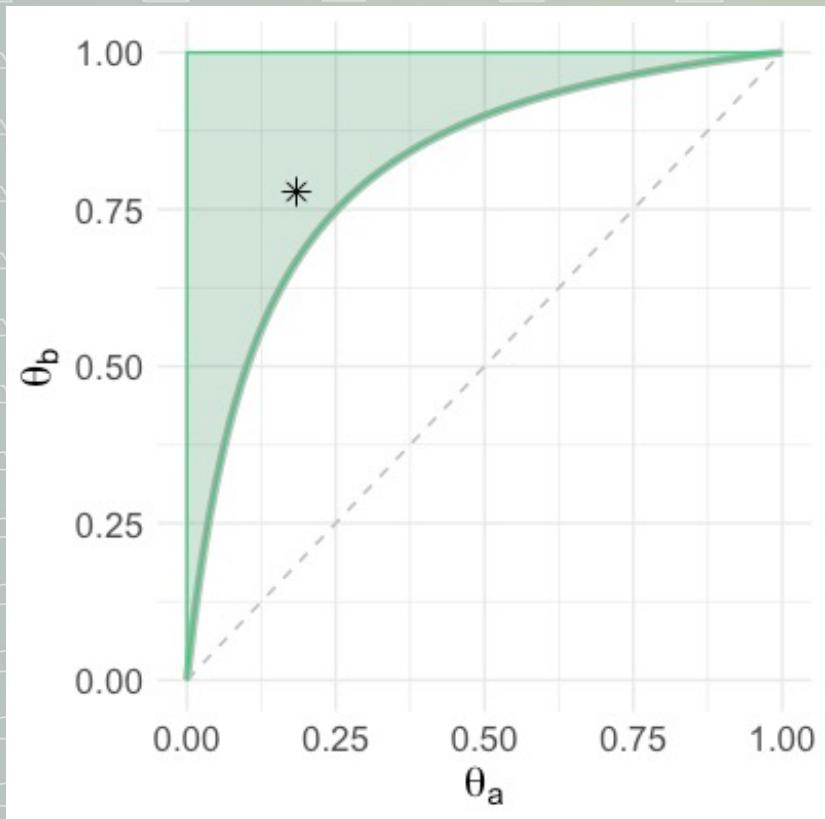


Tricky case: odds ratio and convexity of \mathcal{H}_0

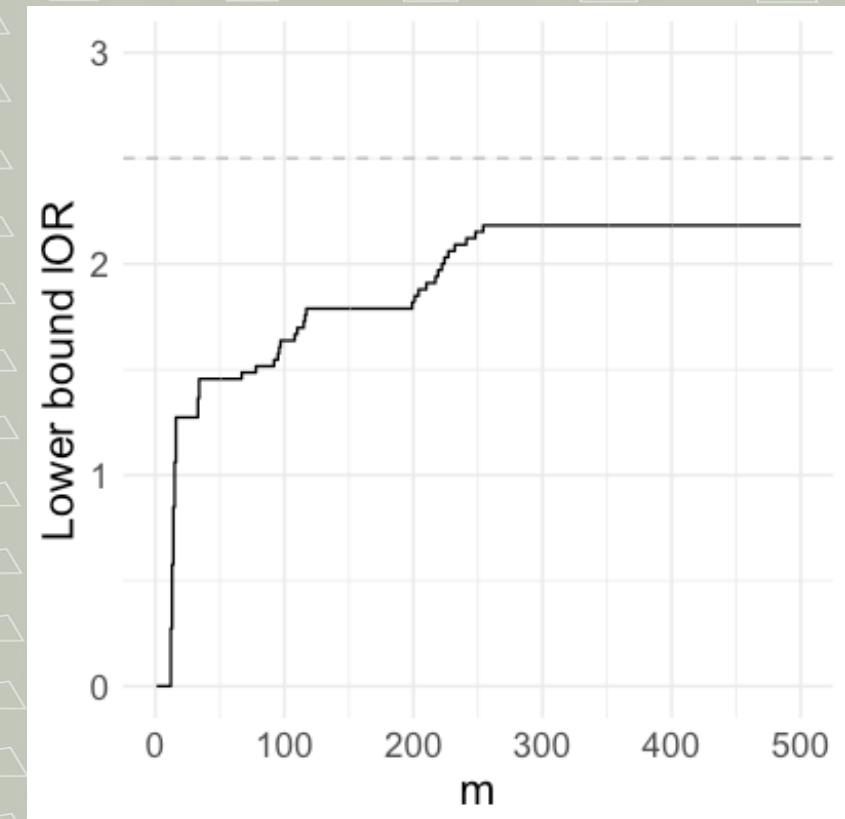
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Simulation: log of the odds ratio

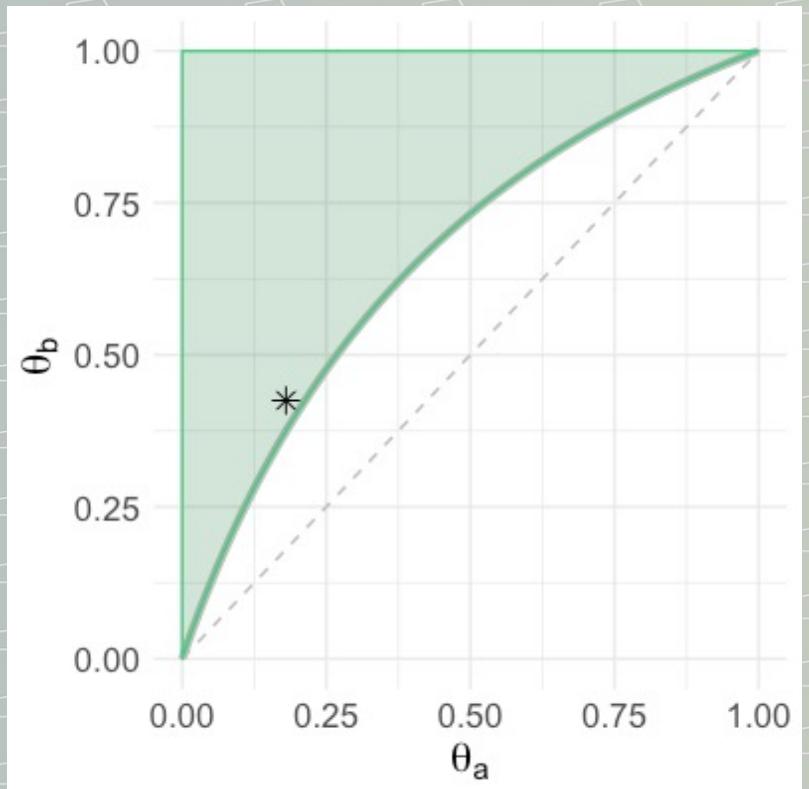


One-sided CS^+ at data block $m = 500$

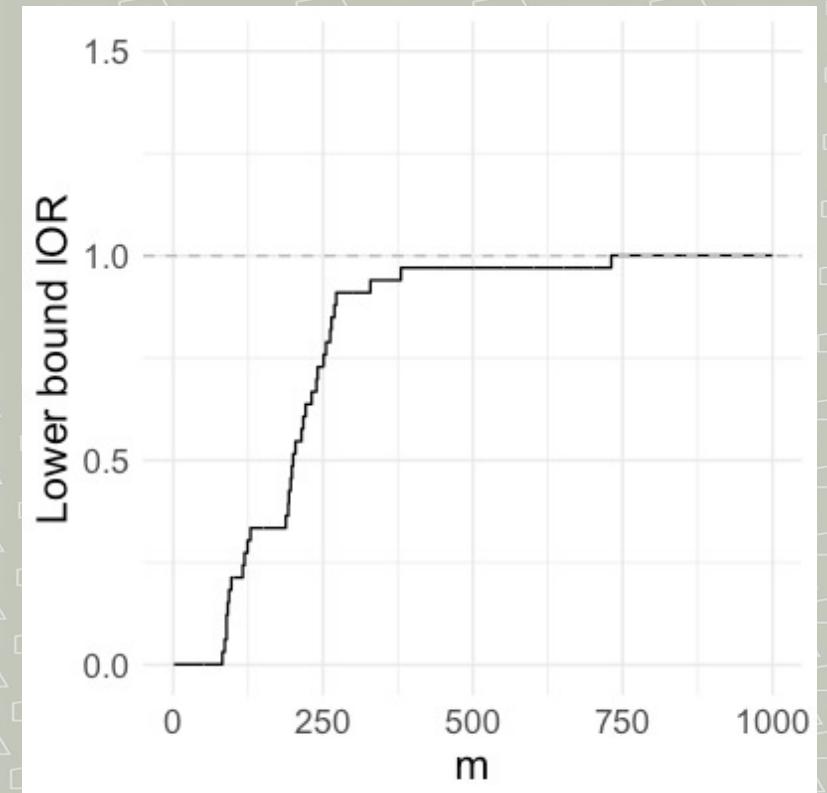


lower bound over time

Simulation: log of the odds ratio



One-sided CS^+ at data block $m = 500$



lower bound over time

Conclusion and novelty

- To our knowledge, really new:
 - **flexibility** (block size, user-specified notions of effect size)
 - **growth rate optimality**: expect evidence for H₁ to **grow as fast as possible** during data collection
- Wald's sequential probability ratio test:
 - Probability ratios can be interpreted as “alternative” E-variables
 - Not growth-rate optimal
 - Only allow for testing odds ratio effect size

Extensions

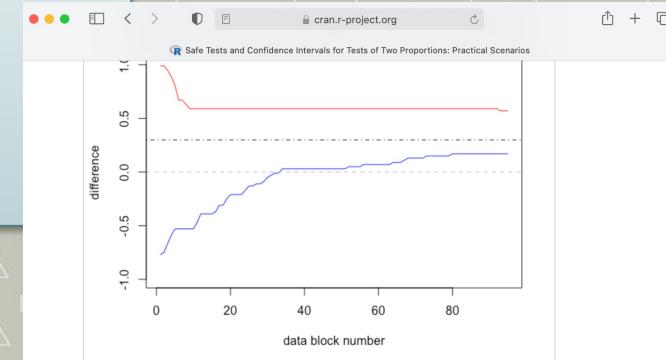
- Beyond Bernoulli: GRO property?
(work by Y. Hao and others)
- Stratified data and conditional independence
 - Use case at UMC Utrecht:
real-time psychiatry research
and recommendations

		Strategy	
		A	B
Stratum 1	Success	$S(A1)$	$S(B1)$
	Failure	$F(A1)$	$F(B1)$
Stratum 2	Success	$S(A2)$	$S(B2)$
	Failure	$F(A2)$	$F(B2)$
Stratum 3	Success	$S(A3)$	$S(B3)$
	Failure	$F(A3)$	$F(B3)$

Further reading and references

- On the theory of E-values:
 - P.D. Grünwald, R. de Heide and W. Koolen (2019) on ArXiv:
- On implementations of E-values:
 - R.J. Turner, A. Ly and P.D. Grünwald (2021) on ArXiv:2106.02693
 - R.J. Turner and P.D. Grünwald (2022) on ArXiv:2203.09785
 - R software: <https://CRAN.R-project.org/package=safestats>

In R console:
install.packages("safestats")



The code below can be used to check that our confidence sequence indeed offers the $1 - \alpha$ guarantee and includes the difference between the two success probabilities of 0.3 in at least 95% of simulated scenarios:

```
coverageSimResult <- simulateCoverageDifferenceTwoProportions(successProbabilityA = 0.2,  
trueDelta = 0.3,  
safeDesign = balancedSafeDesign,  
numberForSeed = 1082021)
```

```
print(coverageSimResult)  
#> [1] 0.974
```