



Issues with Distributed ML in Medical Domain

Privacy

Consider adjacent datasets $d, d' \in \mathcal{D}$ which only differ in one element. The randomized mechanism $\mathcal{M} : \mathcal{D} \rightarrow \mathcal{R}$ is (ϵ, δ) -differentially-private if for any subset of outputs of \mathcal{M} , $S \subseteq \mathcal{R}$

$$\Pr[\mathcal{M}(d) \in S] \leq e^\epsilon \Pr[\mathcal{M}(d') \in S] + \delta \quad (1)$$

where ϵ is the privacy budget, setting the level of intended privacy. The lower the ϵ , the higher the privacy level. δ is a small probability of failure of the DP guarantee. As a rule of thumb, it is set as less than $1/\text{samplesize}$.

Differentially private SGD

- Clip gradients
- Add calibrated noise

Distributed Training

Data Distribution

IID Assumption

Algorithm 1 Federated Averaging

Server side operations for communication round i in $[1..C]$
Input: Updated parameter sets from K participant
Output: Model parameters θ

- if $i = 0$ then
- initialize θ_{global}^i
- else
- wait to receive k parameters sets $\{\theta_1^i, \dots, \theta_k^i\}$
- $\theta_{global}^i = \frac{1}{K} \sum_{k=1}^K \theta_k^i$
- end if
- send θ_{global}^i to K participants

Participant side operations for communication round i in $[1..C]$
Input: Local Training samples X_p , labels Y_p , training epochs E , batch size B , loss function \mathcal{L} , learning rate α
Output: Model parameters θ

- receive θ_{global}^i
- $\theta_k \leftarrow \theta_{global}^i$
- for epoch e in $[1 : E]$ do
- for batch b in $[X_p, Y_p]$ do
- $\theta_k \leftarrow \theta_k - \alpha \nabla \mathcal{L}(b; \theta_k)$
- end for
- end for
- return θ_k

Algorithm 2 Differentially-Private Stochastic Gradient Descent

Input: Training samples X , labels Y , training epochs E , batch size B , loss function \mathcal{L} , clipping threshold C , Gaussian noise scale σ , learning rate α , sampling probability p
Output: Model parameters θ

- Initialize θ
- for epoch e in $[1 : E]$ do
- for batch b sampled from $[X, Y]$ with $\text{prob}(p)$ do
- for each sample b_i in b do
- $g_i \leftarrow \nabla_{\theta} \mathcal{L}(b_i; \theta)$
- end for
- $g_b \leftarrow \frac{1}{|b|} \sum_{i \in b} (g_i / \max(1, \|g_i\|_1 / C)) + \mathcal{N}(0, C^2 \alpha^2 I)$
- end for
- $\theta \leftarrow \theta - \alpha g_b$
- end for
- return θ, ϵ_{spent}

Real world data distribution is non-IID

- Class imbalance: imbalance in target feature
- Feature imbalance: imbalance in non-target feature
- Node imbalance: imbalance in distribution of samples among nodes

Experimental Setup

Dataset

- Census Adult Income dataset
- Income as the target feature, ">50k" as desirable outcome
- Race as the protected feature, "White" as privileged group

Utility Metrics

- Precision
- Recall
- F1-Score

Fairness Metrics

Let $P \subset \mathbb{R}^k \times \{0, 1\}$ be the input space of a binary classifier model. Consider dataset \mathcal{X} with feature set $x : \{x_1, x_2, \dots, x_n\}$ and protected features set $\mathcal{A} \subset x$ and $s_i, s_j \in \mathcal{A}$ tuples of protected feature values. Randomized mechanism $M : \mathcal{X} \rightarrow \mathcal{Y}$ is ϵ -Differentially Fair (DF) with respect to (\mathcal{A}, Θ) if for all $(s_i, s_j) \in \mathcal{A} \times \mathcal{A}$ and $x \sim \theta$:

$$e^{-\epsilon} \leq \frac{P_{M, \theta}(M(x) = y | s_i, \theta)}{P_{M, \theta}(M(x) = y | s_j, \theta)} \leq e^\epsilon,$$

for $\theta \in \Theta$ and $y \in \text{Range}(M)$ where $P(s_i | \theta) > 0, P(s_j | \theta) > 0$ [20].

For $\alpha \notin \{0, 1\}$ and $b_i = (y_{\text{predicted}_i} - y_{\text{label}_i} + 1)$, with N being the number of individual samples in dataset \mathcal{X} the Generalized Entropy Index with mean $\mu = \frac{1}{N} \sum_{i=1}^N b_i$ is defined as:

$$\frac{1}{N\alpha(\alpha-1)} \sum_{i=1}^N \left[\left(\frac{b_i}{\mu} \right)^\alpha - 1 \right]$$

Formally, mechanism M exhibits absolute equal odds -i.e., is fair - for privileged group G' and unprivileged group G'' and desired outcome $O \in \{0, 1\}$ if $\mathbb{E}_{(x,y) \sim G'} [M(x) | y = O] = \mathbb{E}_{(x,y) \sim G''} [M(x) | y = O]$

- Differential Fairness
- Generalized Entropy Index
- Equal Odds Rate

Impact of non-IID Data on Dataset-Level Fairness

- Fairness drops with increase in privacy level
- High privacy regimes act as a regularization method

Impact of non-IID Data on Group-Level Fairness

- Fairness drops with increase in privacy level, impact more prominent on more underprivileged groups
- Non-IID distribution has a negative impact in low privacy regimes, impact less prominent with increase in privacy level

Impact of non-IID Data on Performance

- Performance drops with increase in privacy level
- Recall drops significantly while the difference in precision is prominent but negligible
- High privacy regimes act as a regularization method